

**Fișă de verificare a standardelor minimale pentru abilitare**  
**Conf. dr GAVREA Bogdan-Ionuț**

**I = 5,7989**

**I<sub>recent</sub> = 4,3309**

**C = 31**

**Articole publicate în reviste ISI cu factor de impact > 0.5:**

Numărul publicației	Referință bibliografică	Publicat în ultimii 7 ani (DA sau NU)	s <sub>i</sub>	n <sub>i</sub>	s <sub>i</sub> /n <sub>i</sub>
1	B. Gavrea, "A Hermite–Hadamard type inequality with applications to the estimation of moments of continuous random variables", Applied Mathematics and Computation, ISSN 0096-3003, vol. 254, 92-98, 2015, doi:10.1016/j.amc.2014.12.129.	DA	1,6	1	1,6
2	B. Gavrea, "Improvement of some inequalities of Chebysev–Grüss type", Computers & Mathematics with Applications, ISSN 0898-1221, 64(6), 2003-2010, 2012, doi:10.1016/j.camwa.2012.03.101.	DA	1,996	1	1,996
3	D. J. Cappelleri, P. Cheng, J. Fink, B. Gavrea, V. Kumar, "Automated Assembly for Mesoscale Parts", Automation Science and Engineering, IEEE Transactions on, ISSN 1545-5955, 8(3), 598-613, 2011, doi: 10.1109/TASE.2011.2132128.	DA	2,162	5	0.4324
4	C. Petra, B. Gavrea, M. Anitescu, F. Potra. "A computational study of the use of an optimization-based method for simulating large multibody systems ", Optimization Methods and Software, ISSN 1055-6788, 24(6), 871-894, 2009, doi 10.1080/10556780902806094.	DA	1,21	4	0,3025
5	B. Gavrea, M. Anitescu, F.A. Potra. "Convergence of a Class of Semi-Implicit Time-Stepping schemes for Nonsmooth Rigid Multibody Dynamics", SIAM Journal on Optimization (SIOPT), ISSN 1052-6234, 19(2), 969-1001, 2008, doi: 10.1137/060675745.	NU	2,106	3	0,702
6	B. Gavrea, J. Jaksetic, J. Pecaric. "On a Global Upper Bound for Jessen's Inequality", The ANZIAM Journal, ISSN 1446-1811, 50(02), 246-257, 2008, doi: 10.1017/S1446181109000091.	NU	0,829	3	0,276
7	F.A. Potra, M. Anitescu, B. Gavrea, J. Trinkle. "A linearly implicit trapezoidal method for stiff multibody dynamics with contact, joints and friction". International Journal for Numerical Methods in Engineering, ISSN 0029-5981, 66(7), 1079-1124, 2006, doi:10.1002/nme.1582.	NU	1,961	4	0,490
<b>Total:</b>				<b>I =</b>	<b>5,7989</b>
				<b>I<sub>recent</sub> =</b>	<b>4,3309</b>

**Citări în reviste ISI cu factor de impact > 0.5:**

Numărul publicației care citează	Referință bibliografică a publicației care citează	s <sub>i</sub>
	TITLU ARTICOL: F.A. Potra, M. Anitescu, B. Gavrea, J. Trinkle, "A linearly implicit trapezoidal method for stiff multibody dynamics with contact, joints and friction", International Journal for Numerical Methods in Engineering, ISSN 0029-5981, 66(7), 1079-1124, 2006, DOI 10.1002/nme.1582.	
1	C. Studer, R.I. Leine, Ch. Glocker, "Step size adjustment and extrapolation for time stepping schemes in nonsmooth dynamics", International Journal for Numerical Methods in Engineering, ISSN 0029-5981, Vol. 76, No. 11, pp. 1747-1781, 2008, DOI: 10.1002/nme.2383, <a href="http://onlinelibrary.wiley.com/doi/10.1002/nme.2383/abstract">http://onlinelibrary.wiley.com/doi/10.1002/nme.2383/abstract</a> .	1,961
2	P. Flores, R. Leine, Ch. Glocker, "Application of the nonsmooth dynamics approach to model and analysis of the contact-impact events in cam-follower systems", Nonlinear Dynamics, ISSN 0924-090X, Vol. 69, No. 4, pp. 2117-2133, 2012, DOI: 10.1007/s11071-012-0413-3, <a href="http://rd.springer.com/article/10.1007/s11071-012-0413-3#">http://rd.springer.com/article/10.1007/s11071-012-0413-3#</a>	2,419
3	T. Koziara, N. Bićanić, "Simple and efficient integration of rigid rotations suitable for constraint solvers", International Journal for Numerical Methods in Engineering, ISSN 0029-5981, Vol. 81, No. 9, pp. 1073-1092, 2010, DOI: 10.1002/nme.2711, <a href="http://onlinelibrary.wiley.com/doi/10.1002/nme.2711/abstract">http://onlinelibrary.wiley.com/doi/10.1002/nme.2711/abstract</a>	1,961
4	K. Lee, "A stabilized numerical solution for the dynamic contact of the bodies having very stiff constraint on the contact point", Computational Mechanics, ISSN 0178-7675, Vol. 46, No. 4, pp. 533-543, DOI: 10.1007/s00466-010-0498-9, <a href="http://dx.doi.org/10.1007/s00466-010-0498-9">http://dx.doi.org/10.1007/s00466-010-0498-9</a>	2,044
5	L. Han, J.-S. Pang, "Non-Zenoness of a class of differential quasi-variational inequalities", Mathematical Programming, ISSN 0025-5610, Vol. 121, No. 1, pp. 171-199, 2010, DOI: 10.1007/s10107-008-0230-0, <a href="http://dx.doi.org/10.1007/s10107-008-0230-0">http://dx.doi.org/10.1007/s10107-008-0230-0</a>	1,984
6	J.-S. Pang, "Frictional contact models with local compliance: semismooth formulation", ZAMM - Journal of Applied Mathematics and Mechanics / Zeitschrift für Angewandte Mathematik und Mechanik, ISSN 0044-2267, Vol. 88, No. 6, pp. 454- 471, 2008, DOI: 10.1002/zamm.200600039, <a href="http://dx.doi.org/10.1002/zamm.200600039">http://dx.doi.org/10.1002/zamm.200600039</a>	1,008
7	Lanshan Han, M. Kanat Camlibel, Jong-Shi Pang, W. P. Maurice H. Heemels , "A unified numerical scheme for linear-quadratic optimal control problems with joint control and state constraints", Optimization Methods and Software, ISSN 1055-6788, Vol. 27, No. 4-5, pp. 761-799, 2012, DOI: 10.1080/10556788.2011.593624, <a href="http://www.tandfonline.com/doi/abs/10.1080/10556788.2011.593624">http://www.tandfonline.com/doi/abs/10.1080/10556788.2011.593624</a>	1,210
8	I. Stavness, J. E. Lloyd, Y. Payan, S. Fels, "Coupled hard–soft tissue simulation with contact and constraints applied to jaw–tongue–hyoid dynamics", International Journal for Numerical Methods in Biomedical Engineering, ISSN 2040-7947, Vol.27, No. 3, pp. 367-390, 2011, DOI: 10.1002/cnm.1423, <a href="http://dx.doi.org/10.1002/cnm.1423">http://dx.doi.org/10.1002/cnm.1423</a>	1,542
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10	Xiaogang Xiong, Ryo Kikuuwe, and Motoji Yamamoto, "A Differential Algebraic Method to Approximate Nonsmooth Mechanical Systems by Ordinary Differential Equations," <i>Journal of Applied Mathematics</i> , ISSN 1110-757X, vol. 2013, Article ID 320276, 13 pages, 2013. doi:10.1155/2013/320276, <a href="http://dx.doi.org/10.1155/2013/320276">http://dx.doi.org/10.1155/2013/320276</a>	0,72
11	Bhalerao, K.D., Crean, C., Anderson, K., "Hybrid complementarity formulations for robotics applications", <i>ZAMM - Journal of Applied Mathematics and Mechanics / Zeitschrift für Angewandte Mathematik und Mechanik</i> , ISSN 1521-4001, Vol. 91, No. 5, pp. 386-399, 2011, DOI: 10.1002/zamm.201000093, <a href="http://dx.doi.org/10.1002/zamm.201000093">http://dx.doi.org/10.1002/zamm.201000093</a>	1,008
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TITLU ARTICOL: D. J. Cappelleri, P. Cheng, J. Fink and B. Gavrea, V. Kumar, " <i>Automated Assembly for Mesoscale Parts</i> ", <i>Automation Science and Engineering, IEEE Transactions on</i> , ISSN 1545-5955, 8(3), 598-613, 2011.		
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TITLU ARTICOL: B. Gavrea, M. Anitescu, F.A. Potra. " <i>Convergence of a Class of Semi-Implicit Time-Stepping schemes for Nonsmooth Rigid Multibody Dynamics</i> ", <i>SIAM Journal on Optimization (SIOPT)</i> , ISSN 1052-6234, 19(2), 969-1001, 2008, doi 10.1137/060675745.		

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